### **Code Generation Update**

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# Code Generation with Tasking Event-B

- Tasking Event B is
  - an extension to Event-B.
  - flow control language and annotations.
- Tasking Machines (1) map to task implementations.
- Shared Machines map to protected objects,
  - provide monitor-style protection.
- Environ Machines (2) map to tasks for simulation.

# Code Generation with Tasking Event-B

- Tasking/Environ machines have 'Task Bodies'
  - to describe program flow.
  - which map to program statements.
- Program flow such as,
  - IF event1 ELSE event2 END
  - event1 ; event2
- Events 'populate' sequences, branches, loops, update statements, procedures, procedure calls.

### Since the last RUDW

- Concluded industrial collaboration,
  - Improvements to translator.
  - Java interface for the Environment.
- Templates and code-injection.
- Event-B to FMI-C translation,
  - for use in co-simulation.
- Theory + Java Code for Implementable Sets and Functions.

#### **Improvements to Translators**

- Automatic flattening of invariants, and events.
- Automatic inference of typing annotations and parameter directions.
- ... means fewer steps to generate code from an appropriately constructed model.

For Java integration with Event-B projects,

• To use Java Nature and Java Builder (JDT).

#### Some Items on the To-do List

But, we are still short of the goal, in terms of usability, and features.

- Validation and feedback.
- Translation of nested state-machines.
- Synchronization between events of a state-machine (Other than the current *between-cycles* approach).

#### New: A Java Interface for the Environment



Hardware Interface – most likely manually coded. Simulation Code – can be auto-generated.

#### **New: Templates and Code Injection**

- Short paper in ABZ2014.
- Arose out of Thales' request to think about customisation for deploying on different targets.
- Boilerplate code with injection points.
- Injected code is generated from an Event-B model,
  - using a 'generator' extension point.

### An Example Template

- //## <addToHeader>
- fmiStatus fmiInitializeSlave(fmiComponent c,
  - fmiReal tStart, fmiBoolean StopTimeDefined,
  - fmiReal tStop) {
  - ModelInstance\* comp = (ModelInstance\*) c;
  - //## <initialisationsList>
  - //## <stateMachineProgramCounterIni>
    return fmiOK;
    - Tags are 'processed'. Other lines are output verbatim.

#### **Template Processing**



#### New: Event-B to C, for Co-simulation

- For Advance EU FP7, uses FMI.
- The objective is to,
  - test the generated code in a simulation of its environment.
  - improve performance of simulation.
- Master and Slaves communicate through API.
- Slaves are FMUs.

#### **Event-B to C, for Co-simulation**

- The master is cyclic; slaves are initialized,
  - ... then master does simulate-update cycle.
- We can generate an FMU from an Event-B machine and component diagram.
- We can replace the machine, with the FMU, in the component diagram, and simulate/test with that.
- We can also import FMUs into other simulators.

#### **FMUs from Machines**



### **Current Status**

- Event-B to C code generator Working.
- FMU packager Working.
- Examples pass FMU checkers/simulators
  Win32
  - Linux64
- Component simulation not yet working.
- Dymola Simulator import not yet working.

#### **NEW: Implementable Sets and Functions**

- Translate Sets and Functions to code.
  - Uses the Theory plug-in.
- Depends on target language API,
  - Java HashSet and HashMap.
  - Function domain elements map to keys,
  - Range elements map to values.
- Still experimental.
- Used in PRIME project.

#### **Implementable Sets**

```
THEORY
  SetImpl
TYPE PARAMETERS
  т
OPERATORS
  •setImpl : setImpl(t : T) EXPRESSION PREFIX
  direct definition
   setImpl(t : T) \triangleq \mathbb{P}(T)
  •newSet : newSet(t : ℙ(T)) EXPRESSION PREFIX
  direct definition
   newSet(t : \mathbb{P}(T)) \doteq \emptyset \otimes \mathbb{P}(T)
  •newEnum : newEnum(t : T) EXPRESSION PREFIX
  direct definition
   newEnum(t : T) \doteq \mathbb{P}(T)
  •singleton : singleton(a : T) EXPRESSION PREFIX
  direct definition
    singleton(a : T) \doteq {a}
  •setUnion : setUnion(a : ℙ(T), b : ℙ(T))
  direct definition
    setUnion(a : \mathbb{P}(T), b : \mathbb{P}(T)) \doteq a u b
```

#### **Translation Rules**

TRANSLATOR
Java
Metavariables
■ a ∈ P(T)
■ b $\in \mathbb{P}(T)$
■ t ∈ P(T)
■ s ∈ T
Translator Rules
IntegerType : Z 뻐 Integer
unionRule : setUnion(a,b) 뻐 a.union(b)
<pre>intersectRule : setIntersection(a,b) \model a.intersect(b)</pre>
subtractRule : setSubtract(a,b) ⊨⇒ a.subtract(b)
newSetRule : newSet(ø%₽(t)) ⊨→ new SetImpl <t>()</t>
<pre>setReduceRule : setReduce(a) ⇒ a.getFirst()</pre>
singletonRule : singleton(s) v a ⊨⇒ a.setUnion(s)
newInstanceRule1 : newInst(T) ⊨→ new T()
newInstanceRule2 : newInst2(t,s) ⊨⇒ new t(s)
Type Rules
typeTrns2 : Z 🛏 Integer
typeTrnsl : setImpl(T) ⊨⇒ SetImpl <t></t>
typeTrns3 : newType(T) ⊨⇒ T

#### **Java Set Implementation**

```
package setImpls java;
import java.util.HashSet;
 public class SetImpl<E> extends HashSet<E> {
     /**
Ð
     private static final long serialVersionUID = 26389
Θ
     public SetImpl<E> union(SetImpl<E> otherSet) {
         addAll(otherSet);
         return this;
     }
     public SetImpl<E> intersect(SetImpl<E> otherSet) {
Θ
         retainAll(otherSet);
         return this;
     }
     public SetImpl<E> subtract(SetImpl<E> otherSet) {
Θ
         removeAll(otherSet);
         return this;
     }
     public E getFirst() {
Θ
         Iterator<E> iter = iterator();
         if(iter.hasNext()) return iter.next();
         else return null;
     }
     public SetImpl<E> setUnion(E element) {
Θ
         add(element);
         return this;
     }
 ٦
```

#### **Questions**:

How to improve plug-in development when much of it is *engineering*, not research?

- Academia v Industry: bridging the gap?
- Providing a platform to 'sell' Event-B?

Day-to-day,

- Keeping up with (communicating) changes?
- Compatibility issues?
- ...