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Rodin User + Developer Workshop

Tasking Event-B for Code Generation

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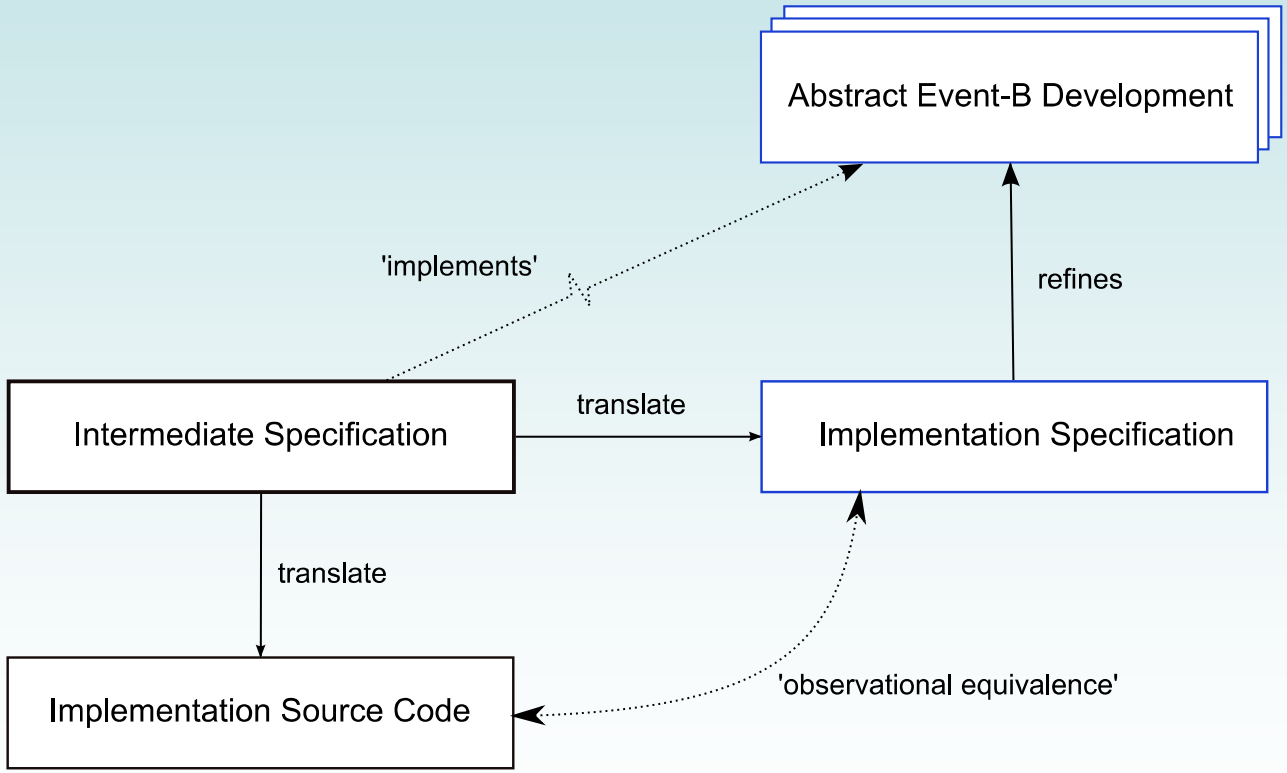
Previous work

OCB – Linking Event-B and Object-Oriented Implementations



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Previous work

The Intermediate Specification (OCB),

- was Object Oriented in style; java-like.
- mapped to a Java implementation.
- had a large semantic gap between the Event-B model and OCB.
- gave rise to difficult refinements, due to the abstraction large gap.

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Tasking Event-B

Tasking Event-B is an extension of Event-B,

- with a smaller semantic gap (between Event-B and Implementation specification) than in previous work.
- with smaller refinement steps which should make proofs easier.
- with translators that map to Ada (and in the future, C).

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Tasking Event-B

Targeting implementations with,

- Multi-tasking capability
- Tasking
  - for shared memory systems.
  - i.e. task/lightweight process/thread.
  - using interleaving atomic executions.
- Sharing data between tasks using ‘protected objects’,
  - using atomic procedure calls,
  - with blocking behaviour.

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Tasking Event-B

Has Loop, Branch, Sequence, and Synchronisation Constructs.

Protected Object's updates Modelled by Shared Event Composition

Events can map to,

- part of a loop /branch implementation.
- a subroutine definition.
- part of a subroutine call (parameters).

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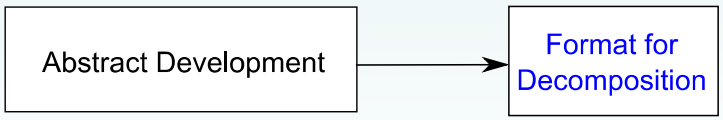
Before Decomposition

1. Specify the abstract development.
2. Prepare for decomposition. For each event,
   - identify and specify parameters (using event guards),
   - substitute expressions by parameters, in event actions, where applicable.



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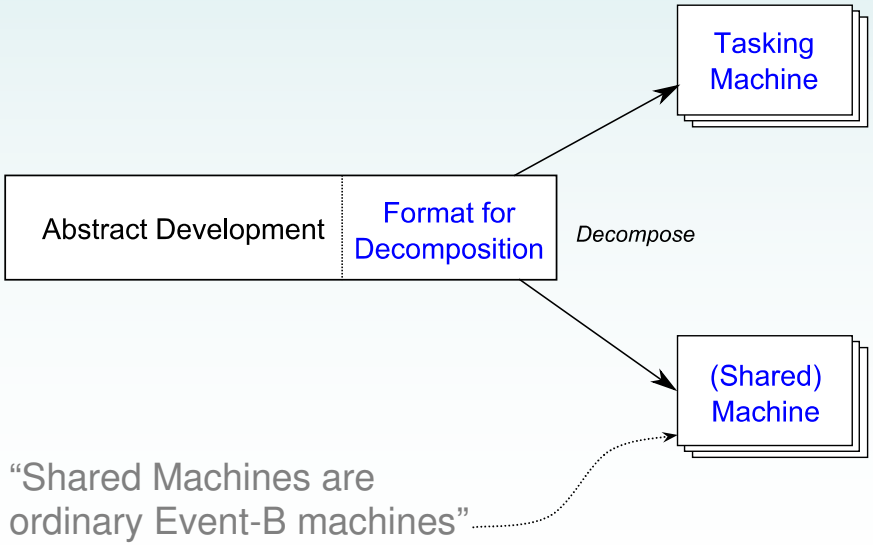
Decompose

3. Allocate variables to machines during shared event decomposition (typically to multiple Tasking/ Shared Machines)

4. Complete the decomposition.



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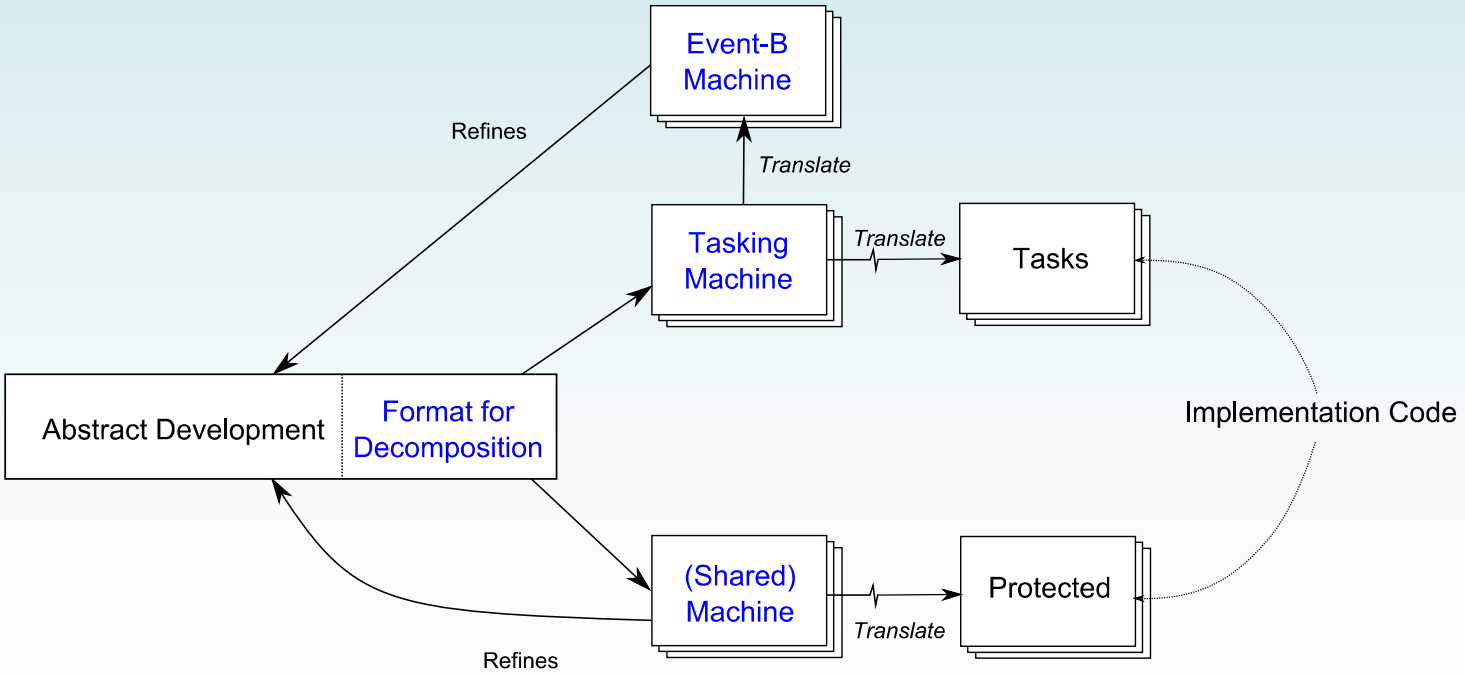
Translation

5. Copy, or reference, decomposed machines for use in the tasking model.

6. Add Tasking Constructs to create Tasking and Shared Machines.
   e.g. synch, loop, branch, sequence, priority, etc.

7. Automatic Translation to Code and Event-B



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Tasking Event-B Notation V1

TaskBody ::=
TaskBody ; *TaskBody*
| **if** EventSynch **endif**
[**elseif** EventSynch **endelseif**] …
[**else** EventSynch **endelse**]
| **do** EventSynch [**finally** EventSynch] **od**
| EventSynch

More details @
http://wiki.event-b.org/images/TranslationV20100722.pdf

tasktype ::= Periodic(p) | One Shot | Repeating | Triggered

priority(n)

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Event Synchronisation

EventSynch ::= LocalEvent RemoteEvent

- Tasking Local/Remote Events are annotated Event-B Events

- Local/remote is relative to a particular task.
  - A local event belongs to a tasking machine,
    and only updates the task's state.
  - A remote event belongs to a shared machine,
    and only updates a shared machine's state.

- Specifies 'synchronisation' of a local and remote events
  - decomposition semantics; guards are conjoined.
  - with parallel updates.

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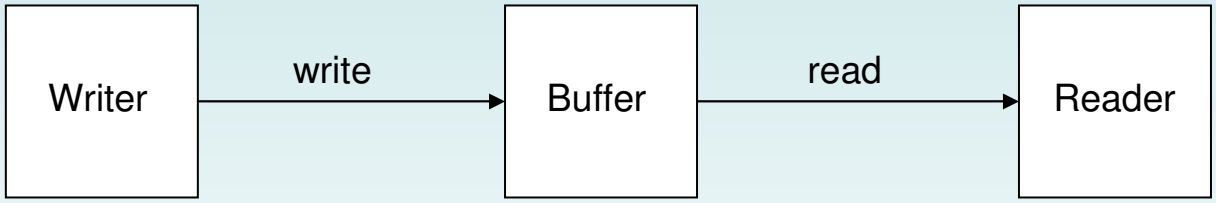
One-Place Buffer Example

"write a single NAT value to buffer"



"read the value from the buffer"

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Abstract Machine

```
machine AbstractBuffer

variables buff wVal rVal wCount sCount

…

  event write
    where
      buff < 0
    then
      buff ≔ wVal
      sCount ≔ sCount + 1
      wCount ≔ sCount + 1
  end
```

“buff is initially -1”

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Parameterised for Decomposition (i)

machine ReadWriteBuffer
refines AbstractBuffer

variables buff wVal rVal wCount sCount

…

event write **refines** write
  any *p1* *p2*
  where
    p1 = wVal
    p2 = sCount + 1
    buff < 0
  then
    buff ≔ *p1*
    sCount ≔ sCount + 1
    wCount ≔ *p2*
end

was buff ≔ wVal

"The parameter wVal"

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Parameterised for Decomposition (ii)

```
machine ReadWriteBuffer
refines AbstractBuffer

variables buff wVal rVal wCount
  sCount

…

  event write refines write
    any p1  p2
    where
      p1 = wVal
      p2 = sCount + 1
      buff < 0
    then
      buff ≔ p1
      sCount ≔ sCount + 1
      wCount ≔ p2
  end
```

was wCount ≔ sCount + 1

"The parameter: sCount + 1"

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Decomposed Machines

machine Writer

variables wVal wCount

…

event write
  any *p1_out* *p2_in*
  where
    p2_in ∈ ℤ
    p1_out ∈ ℤ
    p1_out = wVal
  then
    wCount ≔ *p2_in*
end

machine Shared

variables buff sCount

…

event write
  any *p1_in* *p2_out*
  where
    p2_out ∈ ℤ
    p1_in ∈ ℤ
    p2_out = sCount + 1
    buff < 0
  then
    buff ≔ *p1_in*
    sCount ≔ sCount + 1
end

- Parameter renaming is for clarity only,
  - but parameters will be 'paired' in order of declaration for translation.

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Adding the Tasking Constructs

```
tasking machine Writer
priority 5
tasktype triggered
variables wVal wCount

…

body
  w1: ◁ write || Shared.write ▷ ;
  w2: …

  event sync write
    any
      out p1_out
      in p2_in
    where
      p2_in ∈ ℤ
      p1_out ∈ ℤ
      p1_out = wVal
    then
      wCount ≔ p2_in
  end
```

```
machine Shared

variables buff sCount

  …

  event write
    any
      in p1_in
      out p2_out
    where
      p2_out ∈ ℤ
      p1_in ∈ ℤ
      p2_out = sCount + 1
      buff < 0
    then
      buff ≔ p1_in
      sCount ≔ sCount + 1
  end
```

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The Resulting Event-B model

machine Writer **refines** Writer
sees autoGenCTX_Writer

variables
wVal wCount wCount2 Writer_pc

Invariants
…
Writer_pc ∈ **Writer_pc_Set**

events
event write **refines** write
any *p1_out p2_in*
where
p2_in ∈ ℤ
p1_out ∈ ℤ
p1_out = wVal
Writer_pc = **w1**
then
wCount ≔ *p1_out*
Writer_pc ≔ **w2**
end

machine Shared

variables buff sCount

invariants
… // various typing

event write
any *p1_in p2_out*
where
p2_out ∈ ℤ
p1_in ∈ ℤ
p2_out = sCount + 1
buff < 0
then
buff ≔ *p1_in*
sCount ≔ sCount + 1
end

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The Resulting Event-B model

machine Writer **refines** Writer
sees autoGenCTX_Writer

variables
wVal wCount wCount2 write

Invariants
…
write ∈ BOOL

events
event write **refines** write
any *p1_out* *p2_in*
where
p2_in ∈ ℤ
p1_out ∈ ℤ
p1_out = wVal
write = TRUE
then
wCount ≔ *p1_out*
write ≔ FALSE
end

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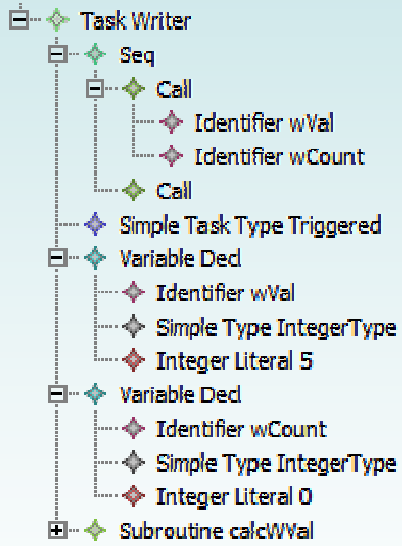
The Writer, Common Language Model

- Common Language Model
  - for further translation to AdaEMF etc.



Task Writer
taskType triggered
Declarations
s: Shared
wVal: Integer := 5
wCount: Integer := 0

Subroutine calcWVal(){
wVal := wVal * 2
}

Task Body
s.write(wVal, wCount);
…

.. or as pretty print

"CLM only needs to be machine readable"

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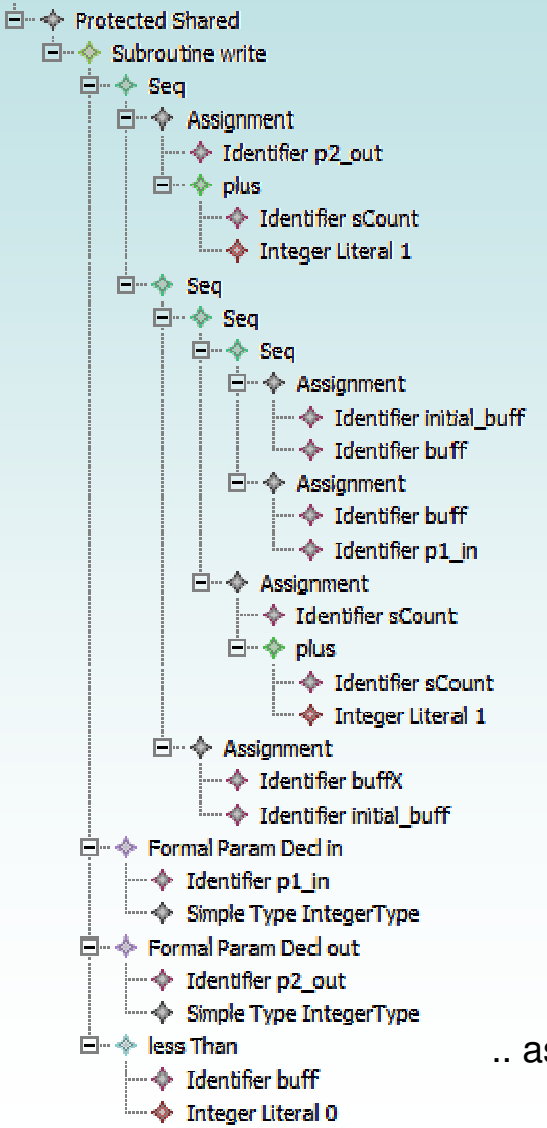
The Shared, Common Language Model



.. as pretty print

Protected Shared
Declarations
buff: Integer := -1
sCount: Integer := 0
buffX: Integer := -1

Subroutine write(p1_in: **in** Integer,
p2_out: **out** Integer)
when buff < 0 {
p2_out := sCount + 1;
initial_buff := buff;
buff := p1_in;
…
}
…

"Conditional waiting in implementations"

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TODO

- Common Language Metamodel V1 to AdaEMF translation,
  - for use with AdaEMF to AdaText Source Translator,
    - from Alexei in Newcastle.

- Testing and Evaluation of Common Language Metamodel V1 and tools.

- Version 2 of the Intermediate Language ??