Algorithms correct by construction à la JRA using EB2Algo

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 JRA proposed many examples of algorithms construction in 2001 with his 2 merges events (algo)

• JRA gave lecture "Analysing and Constructing Computer Programs" from 2014 to 2019

• No many other case study

 No tool to apply JRA's rules except an interactive one but not complete in Shanghai (a student of Li Quin) • JRA asked me to work again on this topics

 more EBRP algorithms: compute the *n* first prime numbers (many versions), bubbelsort, Dutch Flag, Better decomposition, quick sort, merge sort.

instantiation plugin was used for prime numbers (¬*finite*(*Prime*) quicksort (variant), Better decomposition

 After these Rodin developments, I asked Neeraj to develop a tool to produce an algorithm

};

}

```
p[0]= 0; p[1]= n; t = 1;
for(i=0;i<n;i=i+1) g[i]=f[i];</pre>
while (t!=0) {
   if (p[t-1] == p[t] - 1) \{ t = t - 1; \}
   else {
             a=p[t-1]; b=p[t]-1; c=g[(a+b)/2];
             while (a<b)
                if (g[a]<c) {a=a+1;}
                else if (q[b]>c) \{b=b-1;\}
                else {v=g[a];g[a]=g[b];g[b]=v;a=a+1;b=b-1;}
             if (b<a) {k=b;}
             else if (g[a]<=c) {k=b;} else {k=a-1;};
             p[t+1]=p[t];
             p[t] = k+1;
             t=t+1;
      }
```

• It's a sorting program

• at end g contains all values of f but in the order

• a permutation on index of f gives the order

• not easy to see this

It's a sequential version of the famous quicksort

final any PIwhere $PI \in 0..n-1
ightarrow 0..n-1$ $\forall i, j$. $i \in 0..n - 1 \land j \in i..n - 1$ \Rightarrow $f(PI(i)) \leq f(PI(j))$ then g := PI; fend

After seven or eight refinements: 10 events





progress_singl
when

$$topI \neq 0$$

 $stack(topI - 1)$
 $= stack(topI) - 1$
then
 $topI := topI - 1$
end

swap when progress_bsup progress_binf $boolchI \neq 0$ when when binf < bsup $boolchI \neq 0$ $g(binf) \ge pv$ $boolchI \neq 0$ binf < sup $g(bsup) \le pv$ binf < bsup $g(binf) \ge pv$ g(binf) < pvthen g(bsup) > pvthen $g := g \Leftrightarrow \{binf \mapsto g(bsup)\}$ then $, bsup \mapsto q(binf) \}$ bin f := bin f + 1bsup := bsup - 1binf := binf + 1end end bsup := bsup - 1



```
progress

when

boolk \neq 0 boolchI \neq 0 bsup \leq binf

then

stack := stack \Leftrightarrow \{topI \mapsto K + 1, topI + 1 \mapsto stack(topI)\}

boolchI := 0

topI := topI + 1

boolk := 0

end
```

 $boolchI \neq 0 \Rightarrow topI \neq 0 \land stack(topI - 1) \neq stack(topI) - 1$

• At the end of the refinement process we have many small guarded events

 JRA proposed to merge two events (or guarded algorithms) using two merging rules and an additional rule for init.

• when we merge two events we get a guarded algorithm

• some side condition are necessary



- Side Conditions:
 - Both events must have been introduced at the same refinement.
- Special Case: If *P* is missing the resulting "event" has no guard



- Side Conditions:
 - ${m P}$ must be invariant under ${m S}$
 - The first event must have been introduced at one refinement step below the second one.

- Special Case: If P is missing the resulting "event" has no guard

when *P* is not invariant under *S* (or if you cannot prove *P*) JRA said always use the M_IF rule.

 level of the merge event: it's the less one if the abstract one is the small one

• rules defined in 2001 before anticipated events (2005) then I have corrected a little level definition.

• convergent level = level where the event is convergent convlevel(evt)

definition level = level where the event is defined defevel(evt)

level(evt)=convlevel(evt) → defevel(evt)

• lexicographies order

 progress is defined and convergent at level 1, swap is defined at level 0 (g :=) and convergent at level 2 compute_K1 when $boolchI \neq 0$ boolk = 0 bsup < binfthen K := bsup boolk := 1end compute_K2 when $boolchI \neq 0$ boolk = 0 bsup = binf $g(binf) \leq pv$ then K := bsup boolk := 1end compute_K3 when $boolchI \neq 0$ boolk = 0 bsup = binf g(binf) > pvthen K := binf - 1 boolk := 1end $compute_K1$ when $boolchI \neq 0$ boolk = 0 bsup < binf $bsup \leq binf$ then K := bsup boolk := 1end

compute_K2 when $boolchI \neq 0$ boolk = 0 bsup = binf $bsup \leq binf$ $g(binf) \leq pv$ then K := bsup boolk := 1end compute_K3 when $boolchI \neq 0$ boolk = 0 bsup = binf $bsup \leq binf$ g(binf) > pvthen K := binf - 1 boolk := 1end

```
compute_K2_K3
 when
    boolchI \neq 0
    boolk = 0
    bsup \leq binf
    bsup = binf
 then
    if g(binf) \leq pv then
      K := bsup
      boolk := 1
   else
      K := binf - 1
      boolk := 1
   end
 end
```

```
compute_K1_K2_K3
  when
    boolchI \neq 0 bsup < binf boolk = 0
  then
    if bsup < binf then
      K := bsup
      boolk := 1
    else
      if g(binf) \leq pv then
        K := bsup \mid\mid boolk := 1
      else
        K := binf - 1 \mid\mid boolk := 1
      end
    end
  end
```

```
compute_K1_K2_K3_progress
  when
    boolchI \neq 0 \ bsup < binf
  then
    while boolk = 0 do
      if bsup < binf then K := bsup || boolk := 1
      else if g(binf) \leq pv thenK := bsup|| boolk := 1
           elseK := binf - 1 || boolk := 1
           end
      end
    end;
    stack := stack \Leftrightarrow \{topI \mapsto K+1, topI+1 \mapsto stack(topI)\}
    boolchI := 0
    topI := topI + 1
  end
```

A while with one turn in the loop ! *boolk* can disapear.

```
compute_K1_K2_K3_progress
  when
    boolchI \neq 0 \ bsup \leq binf
  then
    if bsup < binf then K := bsup
    else if g(binf) \leq pv thenK := bsup
         elseK := binf - 1
         end
    end;
    stack := stack \Leftrightarrow \{topI \mapsto K+1, topI + 1 \mapsto stack(topI)\}
    boolchI := 0
    topI := topI + 1
  end
```

- Neeraj's constraints: the tool need to be automatic. No interaction. No proof obligations can be generated
- I proposed to compute a guard tree
- guards need to be completed (RED GUARDS)

- the tool try to split a subset of events in two non empty subsets using a guard *G*.
- one subset with all events using *G* as guard and the other one using ¬*G* as guard. Both subsets are splited using the same algorithm (recursive) without guards *G* and ¬*G*. All events are in the union of both subset (partition).
- when there is only one event all guards of this event are consumed.
- It's a backtracking algorithm but *G* is not choiced arbitrary. We take a guard inside an event which has the minimum number of guard (less tentatives). If *G* doesn't work we choice the next guard of the event.
- if the split abord using all guard of the event: A guard misses or there is a deadlock. It's the difficult part for a beginner.

On the guard tree we compute

- the subset of events
- A level: it's the minimum of all events levels of the subset. then we can decide to apply M_IF or perhaps M_WHILE
- the set of guards (above) which are preserved by all events in the subset (for a while)
- With these three attributs we can apply JRA's rules (down-top)

On the guard tree we compute

- the subset of events
- A level: it's the minimum of all events levels of the subset. then we can decide to apply M_IF or perhaps M_WHILE
- We compute the variables which doesn't change by all events in the algorithm (NO substitution on this variable x := ...) then a guard which uses only these variables is preserved. Other can change, we apply a M_IF
- With these four attributs we can apply JRA's rules (down-top)

(topI = 0)[final] $(topI \neq 0)[progress; choiceI; progress_binf; progress_bsup; swap; progress_singI; computeK1; computeK2; computeK3]$ $\begin{array}{l} (topI=0) \ [final] \\ (topI\neq 0) \ [progress; choiceI; progress_binf; progress_bsup; swap; \\ progress_singI; computeK1; computeK2; computeK3] \\ (stack(topI-1)\neq stack(topI)-1) [progress; choiceI; progress_binf; progress_bsup; \\ swap; computeK1; computeK2; computeK3] \\ (stack(topI-1)=stack(topI)-1) [progress_singl] \end{array}$

 $\begin{array}{l} (topI=0) \quad [final] \\ (topI\neq 0) \quad [progress; choiceI; progress_binf; progress_bsup; swap; \\ progress_singI; computeK1; computeK2; computeK3] \\ (stack(topI-1)\neq stack(topI)-1)[progress; choiceI; progress_binf; progress_bsup; \\ swap; computeK1; computeK2; computeK3] \\ (boolchI\neq 0)[progress; progress_binf; progress_bsup; swap; \\ computeK1; computeK2; computeK3] \\ (boolchI=0)[choiceI] \\ (stack(topI-1)=stack(topI)-1)[progress_singl] \end{array}$

(top I = 0) [final] $(topI \neq 0)$ [progress; choiceI; progress_binf; progress_bsup; swap; $progress_singI$; computeK1; computeK2; computeK3] $(stack(topI - 1) \neq stack(topI) - 1)$ [progress; choiceI; progress_binf; progress_bsup; swap; computeK1; computeK2; computeK3] $(boolchI \neq 0)$ [progress; progress_bin f; progress_bsup; swap; computeK1; computeK2; computeK3](boolchI = 0)[choiceI] \neg (*binf* < *bsup*)[*progress*; *computeK*1; *computeK*2; *computeK*3] $(boolk \neq 0)[progress]$ (boolk = 0) [compute K1; compute K2; compute K3] $\neg(binf = bsup)[computeK1]$ (bin f = bsup)[compute K2; compute K3](g(binf)pv)[computeK2] $\neg(q(binf)pv)[computeK3]$ (binf < bsup)[progress_binf; progress_bsup; swap] $(q(binf) < pv)[progress_binf]$ $\neg (q(binf) < pv)[progress_bsup; swap]$ $(q(bsup) > pv)[progress_bsup]$ $\neg(q(bsup) > pv)[swap]$ $(stack(topI - 1) = stack(topI) - 1)[progress_singl]$

(top I = 0) [final] $(topI \neq 0)$ [progress; choiceI; progress_binf; progress_bsup; swap; $progress_singI$; computeK1; computeK2; computeK3] $(stack(topI - 1) \neq stack(topI) - 1)$ [progress; choiceI; progress_binf; progress_bsup; swap; computeK1; computeK2; computeK3] $(boolchI \neq 0)$ [progress; progress_bin f; progress_bsup; swap; computeK1; computeK2; computeK3](boolchI = 0)[choiceI] $\neg(binf < bsup)[progress; computeK1; computeK2; computeK3]$ $(boolk \neq 0)$ [progress] (boolk = 0) [compute K1; compute K2; compute K3] $\neg(binf = bsup)[computeK1]$ (bin f = bsup)[compute K2; compute K3](g(binf)pv)[computeK2] $\neg(q(binf)pv)[computeK3]$ $(binf < bsup)[progress_binf; progress_bsup; swap]$ $(q(binf) < pv)[progress_binf]$ $\neg (q(binf) < pv)[progress_bsup; swap]$ $(q(bsup) > pv)[progress_bsup]$ $\neg(q(bsup) > pv)[swap]$ $(stack(topI - 1) = stack(topI) - 1)[progress_singl]$

```
(top I = 0) [final]
(topI \neq 0) [progress; choiceI; progress_binf; progress_bsup; swap;
           progress\_singI; computeK1; computeK2; computeK3]
    (stack(topI - 1) \neq stack(topI) - 1)[progress; choiceI; progress_binf; progress_bsup;
                                        swap; computeK1; computeK2; computeK3]
        (boolchI \neq 0) [progress; progress_bin f; progress_bsup; swap;
                       computeK1; computeK2; computeK3]
        (boolchI = 0)[choiceI]
            \neg(binf < bsup)[progress; computeK1; computeK2; computeK3]
                  (boolk \neq 0)[progress]
                  (boolk = 0)[computeK1; computeK2; computeK3]
                       \neg(binf = bsup)[computeK1]
                       (bin f = bsup) [compute K2; compute K3]
                             (g(binf)pv)[computeK2]
                             \neg(q(binf)pv)[computeK3]
            (binf < bsup)[progress\_binf; progress\_bsup; swap]
                (q(binf) < pv)[progress\_binf]
                \neg (q(binf) < pv)[progress\_bsup; swap]
                     (q(bsup) > pv)[progress\_bsup]
                    \neg(q(bsup) > pv)[swap]
    (stack(topI - 1) = stack(topI) - 1)[progress\_singl]
```

(top I = 0) [final] $(topI \neq 0)$ [progress; choiceI; progress_binf; progress_bsup; swap; $progress_singI$; computeK1; computeK2; computeK3] $(stack(topI - 1) \neq stack(topI) - 1)$ [progress; choiceI; progress_binf; progress_bsup; swap; computeK1; computeK2; computeK3] $(boolchI \neq 0)$ [progress; progress_bin f; progress_bsup; swap; computeK1; computeK2; computeK3](boolchI = 0)[choiceI] $\neg(binf < bsup)[progress; computeK1; computeK2; computeK3]$ $(boolk \neq 0)[progress]$ (boolk = 0)[computeK1; computeK2; computeK3] $\neg(binf = bsup)[computeK1]$ (binf = bsup)[computeK2; computeK3](q(binf)pv)[computeK2] $\neg (q(bin f)pv) [compute K3]$ $(binf < bsup)[progress_binf; progress_bsup; swap]$ $(q(binf) < pv)[progress_binf]$ $\neg (q(binf) < pv)[progress_bsup; swap]$ $(q(bsup) > pv)[progress_bsup]$ $\neg(q(bsup) > pv)[swap]$ $(stack(topI - 1) = stack(topI) - 1)[progress_singl]$

INITIALISATION

```
(top I = 0) [final]
(topI \neq 0) [progress; choiceI; progress_binf; progress_bsup; swap;
           progress\_singI; computeK1; computeK2; computeK3]
    (stack(topI - 1) \neq stack(topI) - 1)[progress; choiceI; progress_binf; progress_bsup;
                                       swap; computeK1; computeK2; computeK3]
        (boolchI \neq 0) [progress; progress_bin f; progress_bsup; swap;
                       computeK1; computeK2; computeK3]
        (boolchI = 0)[choiceI]
            \neg(binf < bsup)[progress; computeK1; computeK2; computeK3]
                  (boolk \neq 0) [progress]
                  (boolk = 0) [compute K1; compute K2; compute K3]
                       \neg(binf = bsup)[computeK1]
                       (binf = bsup)[computeK2; computeK3]
                             (q(binf)pv)[computeK2]
                             \neg(q(binf)pv)[computeK3]
            (binf < bsup)[progress\_binf; progress\_bsup; swap]
                (q(binf) < pv)[progress\_binf]
                \neg (q(binf) < pv)[progress\_bsup; swap]
                     (g(bsup) > pv)[progress\_bsup]
                    \neg(q(bsup) > pv)[swap]
    (stack(topI - 1) = stack(topI) - 1)[progress_singl]
```

• EB2Algo was developed by Neeraj under the umbrella of EB2ALL

• EB2Algo works on all JRA's examples (RED GUARDS are added using a refinement)

• EB2Algo works on all my EBRP models

• ask Neeraj for a demo

https://www.irit.fr/EBRP/software