
-- Heating_Controller5A.adb

with Ada.Real_Time, Shared_Object1ImplPkg, System.Storage_Elements;
use Ada.Real_Time, Shared_Object1ImplPkg, System.Storage_Elements;

procedure Heating_Controller5A **is**
 shared_Object1ImplInst: Shared_Object1Impl;

task Display_Update_Task1Impl **is**
 pragma Priority(5);
 end Display_Update_Task1Impl;

-- TASK Display_Update_Task1Impl

task body Display_Update_Task1Impl **is**
 Max : **constant** := 95;
 Min : **constant** := 5;
 cttm1 : Integer := 0;
 ttm : Integer := 0;
 sinc_flag : Boolean := FALSE;
 sdec_flag : Boolean := FALSE;
 tm_tt : Integer;
 for tm_tt'Address **use** System'To_Address(16#ef00#);
 state_inc : Boolean;
 for state_inc'Address **use** System'To_Address(16#ef04#);
 state_dec : Boolean;
 for state_dec'Address **use** System'To_Address(16#ef08#);
 period: **constant** Time_Span := To_Time_Span(0.5);
 nextTime: Time := clock + period;

procedure DIDisplay_Target_Temperature **is**
 begin
 tm_tt := ttm;
 end;

procedure DISense_PressIncrease_Target_Temperature **is**
 begin
 sinc_flag := state_inc;
 end;

procedure DISense_PressDecrease_Target_Temperature **is**
 begin
 sdec_flag := state_dec;
 end;

begin
 loop
 delay until nextTime;
 shared_object1implInst.SOGet_Target_Temperature1(cttm1);
 DISense_PressIncrease_Target_Temperature;
 if(cttm1 < Max **and** sinc_flag = TRUE) **then**
 ttm := (cttm1 + 1);
 sinc_flag := FALSE;
 else
 sinc_flag := FALSE;

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    end if;
    DISense_PressDecrease_Target_Temperature;
    if(sdec_flag = TRUE and cttm1 > Min) then
        ttm := (cttm1 - 1);
        sdec_flag := FALSE;
    else
        sdec_flag := FALSE;
    end if;
    shared_object1implInst.SOSet_Target_Temperature(ttm);
    DIDisplay_Target_Temperature;
    nextTime := nextTime + period;
end loop;
end Display_Update_Task1Impl;

task Envir1Impl is
    pragma Priority(5);
end Envir1Impl;

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-- TASK Envir1Impl

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task body Envir1Impl is
    Max : constant := 95;
    Min : constant := 5;
    inc_flag : Boolean := FALSE;
    for inc_flag'Address use System'To_Address(16#ef04#);
    dec_flag : Boolean := FALSE;
    for dec_flag'Address use System'To_Address(16#ef08#);
    ts1 : Integer := 0;
    for ts1'Address use System'To_Address(16#ef14#);
    ts2 : Integer := 0;
    for ts2'Address use System'To_Address(16#ef18#);
    hss : Boolean := FALSE;
    for hss'Address use System'To_Address(16#ef0b#);
    anha : Boolean := FALSE;
    for anha'Address use System'To_Address(16#ef10#);
    ttd : Integer := 25;
    for ttd'Address use System'To_Address(16#ef00#);
    hsa : Boolean := FALSE;
    for hsa'Address use System'To_Address(16#ef20#);
    ctd : Integer := 20;
    for ctd'Address use System'To_Address(16#ef1b#);
    aota : Boolean := FALSE;
    for aota'Address use System'To_Address(16#ef24#);
    period: constant Time_Span := To_Time_Span(0.1);
    nextTime: Time := clock + period;

    procedure ENAlter_Temperature_Sensor1 is
    begin
        ts1 := (ts1 + 1);
    end;

    procedure ENAlter_Temperature_Sensor2 is
    begin
        ts2 := (ts2 + 1);
    end;

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procedure ENAlter_Heater_Status is
begin
    hss := FALSE;
end;

begin
loop
    delay until nextTime;
    if(inc_flag = FALSE) then
        inc_flag := TRUE;
    else if(inc_flag = TRUE) then
        inc_flag := FALSE;
    end if;
    end if;
    if(dec_flag = FALSE) then
        dec_flag := TRUE;
    else if(dec_flag = TRUE) then
        dec_flag := FALSE;
    end if;
    end if;
    ENAlter_Heater_Status;
    ENAlter_Temperature_Sensor1;
    select
    else
        null;
    end select;
    nextTime := nextTime + period;
end loop;
end Envir1Impl;

task Heater_Monitor_Task1Impl is
    pragma Priority(5);
end Heater_Monitor_Task1Impl;

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-- TASK Heater_Monitor_Task1Impl

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task body Heater_Monitor_Task1Impl is
    Max : constant := 95;
    Min : constant := 5;
    hs1 : Boolean := FALSE;
    nha : Boolean := FALSE;
    shs : Boolean := FALSE;
    state_hss : Boolean;
    for state_hss'Address use System'To_Address(16#ef0b#);
    state_nha : Boolean;
    for state_nha'Address use System'To_Address(16#ef10#);
    period: constant Time_Span := To_Time_Span(0.25);
    nextTime: Time := clock + period;

    procedure HMSense_Heater_Status is
    begin
        shs := state_hss;
    end;

    procedure HMActuate_NoHeat_Alarm is
    begin

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    state_nha := nha;
end;

begin
loop
    delay until nextTime;
    HMSense_Heater_Status;
    shared_object1implInst.SOGet_Stored_HeatSource(hs1);
    if(hs1 /= shs) then
        nha := TRUE;
    else
        nha := FALSE;
    end if;
    HMActuate_NoHeat_Alarm;
    nextTime := nextTime + period;
end loop;
end Heater_Monitor_Task1Impl;

task Temp_Ctrl_Task1Impl is
    pragma Priority(5);
end Temp_Ctrl_Task1Impl;

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-- TASK Temp_Ctrl_Task1Impl

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task body Temp_Ctrl_Task1Impl is
    Max : constant := 95;
    Min : constant := 5;
    stm1 : Integer := 0;
    stm2 : Integer := 0;
    avt : Integer := 0;
    cttm2 : Integer := 0;
    hsc : Boolean := FALSE;
    ota : Boolean := FALSE;
    t1 : Integer;
    for t1'Address use System'To_Address(16#ef14#);
    t2 : Integer;
    for t2'Address use System'To_Address(16#ef18#);
    tm_avt : Integer;
    for tm_avt'Address use System'To_Address(16#ef1b#);
    state_hsc : Boolean;
    for state_hsc'Address use System'To_Address(16#ef20#);
    state_ota : Boolean;
    for state_ota'Address use System'To_Address(16#ef24#);
    period: constant Time_Span := To_Time_Span(0.25);
    nextTime: Time := clock + period;

    procedure TCSense_Temperatures is
    begin
        stm1 := t1;
        stm2 := t2;
    end;

    procedure TCCalculate_Average_Temperature is
    begin
        avt := ((stm1 + stm2) / 2);
    end;

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procedure TCDisplay_Current_Temperature is
begin
    tm_avt := avt;
end;

procedure TCActuate_Heat_Source is
begin
    state_hsc := hsc;
end;

procedure TCActuate_OverHeat_Alam is
begin
    state_ota := ota;
end;

begin
loop
    delay until nextTime;
    TCSense_Temperatures;
    TCCalculate_Average_Temperature;
    TCDisplay_Current_Temperature;
    shared_object1implInst.SOGet_Target_Temperature2(cttm2);
    if(avt < cttm2) then
        hsc := TRUE;
    else
        hsc := FALSE;
    end if;
    shared_object1implInst.SOSet_Heat_Source_State(hsc);
    TCActuate_Heat_Source;
    if(avt > Max) then
        ota := TRUE;
    else
        ota := FALSE;
    end if;
    TCActuate_OverHeat_Alam;
    nextTime := nextTime + period;
end loop;
end Temp_Ctrl_Task1Impl;

begin
    null;
end Heating_Controller5A;

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-- Shared_Object1Impl.ads
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package Shared_Object1ImplPkg is

    protected type Shared_Object1Impl is
        procedure SOGet_Target_Temperature1(tm: out Integer);
        procedure SOSet_Target_Temperature(tm: in Integer);
        procedure SOGet_Target_Temperature2(tm: out Integer);
        procedure SOSet_Heat_Source_State(state: in Boolean);
        procedure SOGet_Stored_HeatSource(state: out Boolean);
    private

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    ctm : Integer := 0;  
    shss : Boolean := FALSE;  
    cttm : Integer := 0;  
end Shared_Object1Impl;  
end Shared_Object1ImplPkg;
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-- Shared_Object1Impl.adb

```
package body Shared_Object1ImplPkg is  
  protected body Shared_Object1Impl is  
    procedure SOGet_Target_Temperature1(tm: out Integer) is  
    begin  
      tm := cttm;  
    end;  
    procedure SOSet_Target_Temperature(tm: in Integer) is  
    begin  
      cttm := tm;  
    end;  
    procedure SOGet_Target_Temperature2(tm: out Integer) is  
    begin  
      tm := cttm;  
    end;  
    procedure SOSet_Heat_Source_State(state: in Boolean) is  
    begin  
      shss := state;  
    end;  
    procedure SOGet_Stored_HeatSource(state: out Boolean) is  
    begin  
      state := shss;  
    end;  
  end Shared_Object1Impl;  
end Shared_Object1ImplPkg;
```