Tasking Event-B Translations

A. Edmunds

July 13, 2010

1 Tasking Event-B Machines to IL1

Source	Target
Tasking Machine	Task (DataType)
AutoTask Machine	Task (non-DataType / only run on start-up)
Shared Machine	Protected Object (DataType)

Tasking and shared machine events map to Subroutine declarations.

Each reference to an event in the control construct is either 'local' or 'remote' with respect to a task. Remote events, used in looping and branching constructs, have no guards (or they have trivially true guards). Local events used in the *EventWrapper* construct have no guards.

2 Synchronized Local/Remote Events

In order to represent the combined updates on local and remote machines in the tasking language we introduce synchronized event composition, for events of tasking/shared machines. In the following discussion we compose one local and one remote event e_l and e_r respectively using $\|e_r$; where the remote event does not have any guards. We define the combined event e as

$$e \triangleq e_l \parallel_e e_r \tag{1}$$

In version1 of the tasking language local and remote machines do not share state, the variables of the guards and actions are disjoint. We can write the individual assignments of $e \triangleq e_l \parallel_e e_r$ in the following way, $e_l, x_1, ..., x_j := y_1 ... y_j$ and the assignments of $e_r, x_{j+1}, ..., x_n := y_{j+1} ... y_n$. When composed in parallel we have,

$$e_l \parallel_e e_r \triangleq g_l \to x_1, \dots, x_n := y_1 \dots y_n \tag{2}$$

When events are used in an EventWrapper construct, the implementation maps to a blocking call. In this case it makes no sense to have a guard on the local

event since the calling task should not block itself. So we only guard the remote event. We define the compound event e as,

$$e = a_l \parallel_e g_r \to a_r \tag{3}$$

When we use IfThenElse or While constructs, we restrict the use of guards to the local event only. We prohibit the use of guards in remote events to avoid complications due to interleaving with other tasks. Our previous work, with OCB, had a similar constraint for the same reason; and the restriction also allows the developer to reason about the effects in a clear way (problem with false else guards!!). This also means that it makes no sense to write a branch without a guarded local event, since the remote event has no guards, if(true) then a endif is simply equivalent to the update a.

A compound event e is defined as,

$$e = g_l \to a_l \parallel_e a_r \tag{4}$$

If one of the events, either local or remote, is not specified in the control construct then the missing event is interpreted as,

2.1 Tasking - Parallel Events to IL1

Control	IL1
$Control1\ ;\ Control2$	Control1; Control2
${\tt EventWrapper}\ e$	call $e_l()$; call $target.e_r()$
$e = e_l \parallel_e e_r$	
$L\colon extsf{DO}\ e\ extsf{OD}$	In task body:
$e = g_l \to a_l \parallel_e e_r$	while (g_l) {
	call $L_{er}($); a_l ;
	}
	In Protected:
	subroutine $L_{er}($){ $a_r;$ }
$L\colon extsf{DO}\ e_1$ FINALLY e_2 OD	In task body:
$e_x = g_{xl} \to a_{xl} \parallel_e e_{xr}$	while(g_{1l}){
	call L_{e1r} (); a_{1l} ;
	}
	call $e_{2r}()$; a_{2l} ;
	In Protected:
	subroutine L_{e1r} (){ a_{1r} ;}

Control	IL1
$L\colon$ IF e_1 ENDIF [ELSEIF e_x ENDELSEIF] [ELSE e_n ENDELSE]	In task body: [if(g_{1l}){ $body$ }] [elseif(g_{xl}){ $body$ }] [else{ $body$ }]
$ \begin{aligned} \mathbf{x} &\in 1 \dots n \\ e_x &= g_{xl} \to a_{xl} \parallel_e e_{xr} \end{aligned} $	
	$body \triangleq \\ call \ L_{exr}(); \ a_{xl}$
	and in Protected: subroutine $L_{exr}() \{ a_{xr} \}$

2.2 Tasking - Parallel Events to Event-B

2.2.1 Using Labelled Clauses

In the following table we use e_l to indicate an event that is local to a task, and e_r to indicate a (remote) event belonging to a shared machine.

Control	Event-B
$Control1\ ;\ Control2$	Control1; Control2
$L\colon ext{ EventWrapper } e$ $e riangleq a_l \parallel_e g_r o a_r$	$egin{array}{c} e_l & riangleq \ \mathbf{WHEN} \ pc_t = L \ \mathbf{THEN} \ a_l \ \parallel \ pc_t := next(L) \ \mathbf{END} \end{array}$
	$e_r \triangleq $ WHEN g_r THEN a_r END
$L\colon \mbox{DO }e \mbox{ OD } \ e=g_l ightarrow a_l \parallel_e a_r$	$egin{aligned} e_{lwhile} &\triangleq \ \mathbf{WHEN} \ g_l \ \land \ pc_t = L \ \mathbf{THEN} \ a_l \ &= \mathbf{END} \ e_{rwhile} &\triangleq \ \mathbf{WHEN} \ \top \ \mathbf{THEN} \ a_r \ &= \mathbf{END} \ \end{aligned}$ $egin{aligned} e_{lwhilefalse} &\triangleq \ \mathbf{WHEN} \ \neg g_l \ \land \ pc_t = L \ \end{aligned}$
	THEN $pc_t := next(L)$ END
$L\colon ext{DO } e_1 ext{ FINALLY } e_2 ext{ OD } e_x = g_{xl} o a_{xl} \parallel_e a_{xr}$	$\begin{array}{l} e_{lwhile} \triangleq \\ \textbf{WHEN} \ g_{1l} \ \land \ pc_t = L \\ \textbf{THEN} \ a_{1l} \\ \textbf{END} \\ e_{rwhile} \triangleq \\ \textbf{WHEN} \ \top \\ \textbf{THEN} \ a_{1r} \\ \textbf{END} \\ e_{lfinally} \triangleq \\ \textbf{WHEN} \ \neg g_{1l} \ \land \ g_{2l} \ \land \ pc_t = L \\ \textbf{THEN} \ a_{2l} \parallel \ pc_t := next(L) \\ \textbf{END} \\ e_{rfinally} \triangleq \\ \textbf{WHEN} \ \top \\ \textbf{THEN} \ a_{2r} \\ \textbf{END} \end{array}$

Control	Event-B
$L\colon$ IF e_1 ENDIF [ELSEIF e_x ENDELSEIF] [ELSE e_n ENDELSE]	$egin{aligned} e_{lif} &\triangleq \ \mathbf{WHEN} \ g_{1l} \ \land \ pc_t = L \ \mathbf{THEN} \ a_{1l} \parallel \ pc_t := next(L) \ \mathbf{END} \end{aligned}$
$e_x = g_{xl} \to a_{xl} \parallel_e a_{xr}$	$egin{array}{l} e_{rif} & riangle & \\ \mathbf{WHEN} & \top & \\ \mathbf{THEN} & a_{1r} & \\ \mathbf{END} & & \end{array}$
	$ \begin{vmatrix} e_{lelseif_x} \triangleq \\ \mathbf{WHEN} $
	$egin{array}{l} e_{relseif_x} & riangle & \\ \mathbf{WHEN} & \top & \\ \mathbf{THEN} & a_{rx} & \\ \mathbf{END} & & \end{array}$
	$\begin{vmatrix} e_{lelse_x} \triangleq \\ \mathbf{WHEN} $
	$e_{relse_x} \triangleq $ WHEN \top THEN a_{nr} END

2.2.2 Without Labelled Clauses

In the following table we use e_l to indicate an event that is local to a task, and e_r to indicate a (remote) event belonging to a shared machine.

Control	Event-B
Control1; Control2	Control1; Control2
EventWrapper e $e riangleq a_l \parallel_e g_r o a_r$	$en_l \triangleq$ WHEN $en = TRUE$ THEN $a_l \parallel en := FALSE \parallel$ $next(en) := TRUE$
	END $e_r \triangleq \\ \text{WHEN } g_r \\ \text{THEN } a_r \\ \text{END}$
DO e OD $e_x = g_l \rightarrow a_l \parallel_e a_r$	$e_{lwhile} \triangleq \ \mathbf{WHEN} \ g_l \ \land \ en = TRUE \ \mathbf{THEN} \ a_l$
$e_x - g_l \rightarrow u_l \parallel_e u_r$	$e_{rwhile} \triangleq \\ WHEN \top \\ THEN a_r \\ END$
	$e_{lfinally} \triangleq \ \mathbf{WHEN} \ \neg g_l \ \land \ en = TRUE \ \mathbf{THEN} \ en := \ FALSE \parallel \ next(en) := TRUE \ \mathbf{END}$
DO e_1 FINALLY e_2 OD	$e_{lwhile} \triangleq $ WHEN $g_{1l} \wedge en = TRUE$
$e_x = g_{xl} \to a_{xl} \parallel_e a_{xr}$	THEN a_{1l} END $e_{rwhile} \triangleq$ WHEN \top THEN a_{1r} END
	$\begin{array}{l} e_{lfinally} \triangleq \\ \mathbf{WHEN} \ \neg g_{1l} \ \land \ en = TRUE \\ \mathbf{THEN} \ a_{2l} \parallel \ en := \ FALSE \parallel \\ next(en) := TRUE \\ \mathbf{END} \\ e_{rfinally} \triangleq \\ \mathbf{WHEN} \ \top \\ \mathbf{THEN} \ a_{2r} \\ \mathbf{END} \end{array}$

Control	Event-B
$L\colon$ IF e_1 ENDIF	$e_{lif} \triangleq$
[ELSEIF e_x ENDELSEIF]	WHEN $g_{1l} \wedge en = TRUE$
[ELSE e_n ENDELSE]	THEN $a_{1l} \parallel en := FALSE$
	next(en) := TRUE
	END
$e_x = g_{xl} \to a_{xl} \parallel_e a_{xr}$	$e_{rif} \triangleq$
	WHEN T
	THEN a_{1r}
	END
	$e_{lelseif_x} \triangleq$
	WHEN $\wedge \neg g_{l1(x-1)} \wedge g_{lx} \wedge$
	en = TRUE
	THEN $a_{lx} \parallel next(en) := TRUE \parallel$
	en := FALSE END
	 .
	$e_{relseif_x} \triangleq $ WHEN \top
	THEN a_{rx}
	END
	$e_{lelse_x} \triangleq$
	WHEN $\wedge \neg g_{1(n-1)l} \wedge$
	en = TRUE
	THEN $a_{nl} \parallel next(en) := TRUE \parallel$
	en := FALSE
	END
	$e_{relse_x} \triangleq$
	ightharpoons WHEN op
	THEN a_{nr}
	END